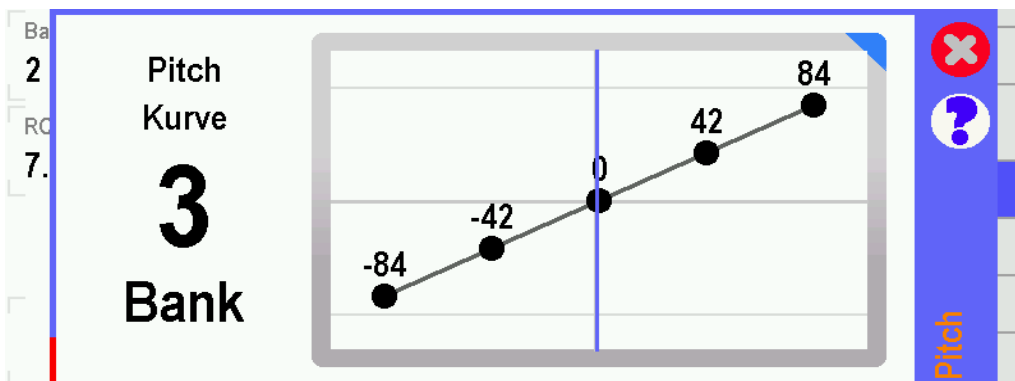
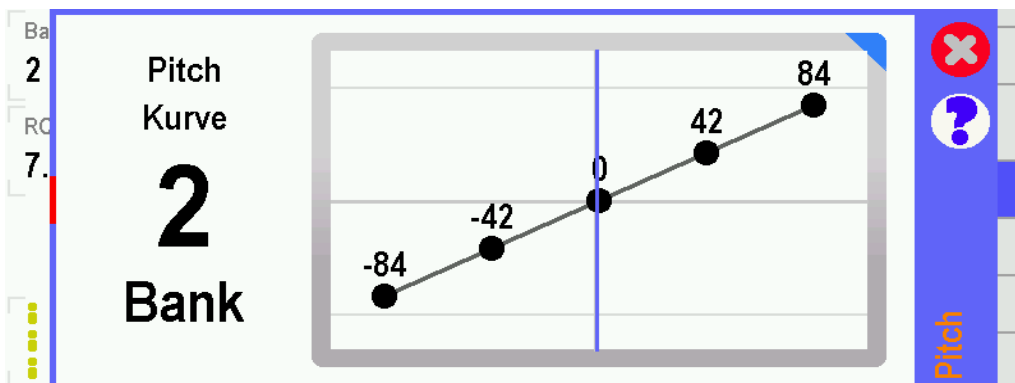
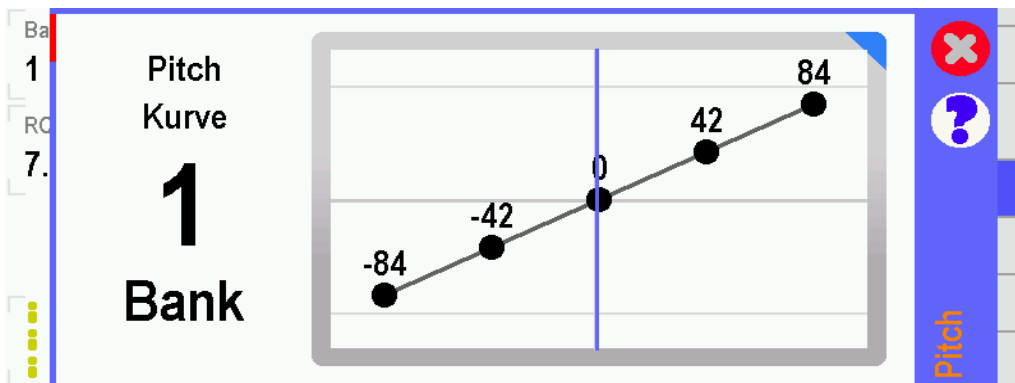


**Pitchkurvenwerte in allen 3 Flugzuständen gleich.  
Pitch values are the same in all 3 flight conditions.**

-84 = -7°  
-42 = -1°  
0 = +5°  
42 = +11°  
84 = +17°



## Hauptrotorwerte / main rotor values

Ba		1	2	3	AR	
1	Hauptrotor					
RC	Exponential	15	40	60	10	
7.	Wendigkeit	70	70	70	90	Hauptrotor
	Empfindlichkeit	70	60	50	75	

Ba		1	2	3	AR	
1	Hauptrotor					
RC	Style	80	80	80	100	
7.	Nick Prekomp.	10	10	10	10	Hauptrotor
	Paddelsim	0	0	0	10	

Ba		1	2	3	AR	
1	Hauptrotor					
RC	Integral	60	50	45	60	
7.	Pitch Pump	0	0	0	0	Hauptrotor
	Pitch Balance	30	30	20	-1	

Ba		1	2	3	AR	
1	Hauptrotor					
RC	Optimierer Werte	35	35	35	45	
7.	Optimierer	<input type="checkbox"/> Aktivieren				Hauptrotor
	Ansprechverhalten	Helikopter Grösse			60	

## Heckrotorwerte / tail rotor values

Ba	1	Heckrotor	1	2	3	AR	
RC	7.	Exponential	60	65	70	50	?
		Drehrate	80	75	70	100	
		Empfindlichkeit	60	30	25	75	

Ba	1	Heckrotor	1	2	3	AR	
RC	7.	Proportional	80	80	80	80	?
		Integral	60	60	60	60	
		I Limiter	-1	-1	-1	-1	

Ba	1	Heckrotor	1	2	3	AR	
RC	7.	I Entladung	-1	-1	-1	-1	?
		Differential	0	0	0	0	
		Pitch Prekomp.	22	22	22	22	

Ba	1	Heckrotor	1	2	3	AR	
RC	7.	Zykl. Prekomp.	8	8	8	8	?
		Stop Gain A	0	0	0	20	
		Stop Gain B	0	0	0	20	

Ba	1	Heckrotor	1	2	3	AR	
RC	7.	Optimierer A	40	40	30	30	?
		Optimierer B	40	40	40	30	
		<input type="checkbox"/> Auto Opti	Beschleunigung			55	

# Reglerwerte für 10S- Setup mit den empfohlenen Komponenten

ESC- values for the 10S- setup with the recommended components

The screenshot shows a control interface for an external controller. The main title is "Externer Regler". Below the title, there are three output channels labeled "Ausgabe". Each channel has a numerical value and a green progress bar. The values are 50, 65, and 82. On the right side, there is a vertical bar with a question mark icon and the text "Ext regler".

Channel	Value
1	50
2	65
3	82